Memory cross Volterra model for Doherty power amplifier with group delay mismatch

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Abstract A Memory Cross Volterra model for Doherty power amplifiers (PA) with delay mismatch is presented in this letter. During the design process of Doherty power amplifier, gain, efficiency and operation bandwidth are mostly considered. Delay mismatch is difficult to avoid in this kind of dual-path circuit, which reduces the modeling performance of traditional behavioral models. The proposed Memory Cross Volterra Model (MCVM) is derived from the combination of three memory polynomial equations with delay mismatch. Simulation results show that the proposed MCVM has about 10 dB improvement in Normalized Mean Square Error (NMSE) compared to Generalized Memory Polynomial (GMP) with the same model complexity level as GMP. In a measurement experiment, a Doherty PA is tested at 3.45 GHz with 20 MHz LTE signal. Compared with GMP, the proposed MCVM has a maximum 2.5 dB improvement in Adjacent Channel Power Ratio (ACPR), and the inverse modeling Normalized Mean Square Error (NMSE) is improved from -41.7 to -44.3 .

Keywords: behavioral model, power amplifier, Doherty, digital predistortion

Classification: Microwave and millimeter-wave devices, circuits, and modules

1. Introduction

Power Amplifiers (PA) are the critical power component in modern communication systems [1]. The efficiency of PA has a significant influence on the energy consumption of the whole system [2]. In recent decades, various advanced efficiency enhancement techniques are proposed in academics, such as harmonic control, Doherty amplifiers, outphasing and envelop tracking [3]. In these techniques, Doherty Power Amplifiers are preferred in commercial base-stations because of the good back-off efficiency which is suitable for communication signals with high Peak Average Power Ratio (PAPR).

In a Doherty PA, the input match network and output match network have to be designed carefully to make the two transistors work appropriately [4, 5]. Especially the phase alignment which affects the power efficiency significantly [6, 7]. Many researchers have paid the phase adjustment much attention. However, the phase alignment is not equal to

group delay alignment. The group delay mismatch may cause a complicated memory effect and bad linearity for Doherty PAs [8].

Linearization components such as digital predistortion (DPD) [1] are also an important subsystem of a transmitter. In recent years, novel applications bring new requirements and challenges for DPD system [9, 10, 11, 12]. Multiple kinds of behavioral models have been developed for modeling and predistortion in DPD system [1], such as Memory Polynomial [13, 14, 15], Dynamic Deviation Reduction (DDR) [16, 17, 18], Generalized Memory Polynomial (GMP) [19, 20, 21], piece-wise model [22, 23], and box oriented models [24]. These models have good performance for most PAs. These models do not focus on the nonlinearity with a group delay mismatch. Deep Neural Network-Based Models are reported to have good performance for Doherty amplifiers [25, 26]. However, a large number of coefficients of Deep Neural Network Model (more than 1000) make these kinds of models difficult to be applied in real application due to the hardware and computing consumption.

This letter proposes a Memory Cross Volterra Model which is suitable for nonlinear systems with group delay mismatch. The model is derived from the combination of RF form memory polynomial with different group delays. Simulations and experiments are performed to prove the validity of the MCVM.

2. Memory cross Volterra model

Assume the two nonlinear branches have different group delays. The combination of these two signals also has a weak static nonlinear effect due to the non-ideal power combination. The nonlinear process of each branch is represented by RF form memory polynomial model. The output in RF expression of this system is given by:

$$\tilde{y} = \sum_{k_0=1}^{K_0} (a_1 \tilde{y}_1 + a_2 \tilde{y}_2)^{k_0} \quad (1)$$

$$\tilde{y}_1 = \sum_{k_1=1}^{K_1} \sum_{m_1=0}^{M_1} b_{k_1, m_1} \tilde{x}(n - m_1)^{k_1} \quad (2)$$

$$\tilde{y}_2 = \sum_{k_2=1}^{K_2} \sum_{m_2=M_s}^{M_s+M_2} b_{k_2, m_2} \tilde{x}(n - m_2)^{k_2} \quad (3)$$

where y_1 and y_2 are the nonlinear output of branch 1 and branch 2. M_1 and M_2 are the memory depth of each branch.

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M_s is the delay factor of the two branch. In order to derive the base-band expression of this system, let:

$$\tilde{x} = \text{Re} \{ e^{jw_0 n} x(n) \} = \frac{e^{jw_0 n} x(n) + e^{-jw_0 n} x^*(n)}{2} \quad (4)$$

Substitute Eq. (4) into Eq. (2) and Eq. (3). To simplify the expression, let $\xi_{m_1} = x(n - m_1)$ and $\psi_{m_2} = x(n - m_2)$

$$y = \sum_{q_2=0}^{K_2} \sum_{q_1=0}^{K_2} \sum_{p_2=0}^{K_1} \sum_{p_1=0}^{K_1} \sum_{m_2=M_s}^{M_s+M_2} \sum_{m_1=0}^{M_1} b_{m_1 m_2 p_1 p_2 q_1 q_2} \xi_{m_1}^{p_1} (\xi_{m_1}^*)^{p_2} \psi_{m_2}^{q_1} (\psi_{m_2}^*)^{q_2} e^{jw_0 n(p_1+q_1-p_2-q_2)} \quad (5)$$

This is a kind of subseries of Volterra series [1]. The next step is to choose the proper terms, which have the major non-linear influence in the Eq. (5). Criterion 1 is that the terms represent the component at the carrier frequency. Criterion 2 is that the major memory depth is related to the shorter delay. Select terms based on the criterion. After removing the carrier term $e^{jw_0 n}$, the base-band expression of the proposed Memory Cross Volterra Model is given by:

$$y = \sum_{d=1}^4 \sum_{k=0}^K \sum_{m_1=0}^{M_1} \sum_{m_2=M_s}^{M_s+M_2} b_{m_1 m_2 k d} \xi_{m_1}^k B_{m_1 m_2 d}^k \quad (6)$$

where the definition of $B_{m_1 m_2 d}$ is given by: $B_{m_1 m_2 1} = \xi_{m_1} \xi_{m_1}^*$, $B_{m_1 m_2 2} = \xi_{m_1} \psi_{m_2}^*$, $B_{m_1 m_2 3} = \xi_{m_1}^* \psi_{m_2}$, $B_{m_1 m_2 4} = \psi_{m_2} \psi_{m_2}^*$

3. Simulation results

In this section, simulations are performed to verify the non-linear modeling ability of the proposed MCVM. The block diagram of the simulation is shown in Fig. 1. Saleh models [27] are applied to represent the nonlinear effect of a complex nonlinear system with delay mismatch. Two Saleh models Eq. (7) stand for the transistors of peak amplifier and carrier amplifier. Another Saleh model that has weak non-linear stands for the non-ideal effect of the combiner. Extra loop delay is added in one of y_2 branch. In the simulation, the $x(n)$ is an LTE signal with 20 MHz bandwidth. The sample speed of $x(n)$ is 122.88 Msa/s. For comparison, Memory Polynomial (MP) [13] and Generalized Memory Polynomial (GMP) Models [19] are also applied to model the output of the nonlinear system. The model coefficients for all three models are calculated by the Least Square algorithm [1].

$$y(n) = \frac{a_1 |x(n)|}{1 + b_1 |x(n)|^2} \exp \left(\psi + \frac{a_2 |x(n)|^2}{1 + b_2 |x(n)|^2} \right) \quad (7)$$

The nonlinear order and memory depth settings of MP are 8 and 4. The nonlinear order and memory depth of GMP are 8 and 4. Lagging and leading depth are both 2. The parameter setting of MCVM is given as following: The

Fig. 1 Block diagram of simulation

Fig. 2 Simulation result in NMSE with different integer delay of y_2 branch.

nonlinear order K is 4 (the equivalent highest polynomial order is 8 because $B_{m_1 m_2 d}$ is a 2 order term). The memory depth of the first and second branches (M_1 and M_2) are 3 and 1. The branch delay (M_s) is changing with the simulation delay L . The coefficient number of MP, GMP, and MCVM are 81, 160 and 160 correspondingly.

The forward modeling performance in Normalized Mean Square Error (NMSE) with different branch delay L shown in Fig. 2. All three models show an accuracy reduction with the increment of the branch delay. The proposed MCVM has better NMSE than GMP and MP when L is changed from 1 to 10. However, when the L is larger than 6, all these three models shows not enough modeling ability for such a complicated nonlinear system.

4. Experimental results

Digital predistortion experiments are performed to prove the performance of the proposed MCVM. A symmetry Doherty PA with post-matching network is applied as the device under test (DUT) in this experiment. Two transistors are both CGHV27015 from Cree. The operating frequency bandwidth of the PA is 3.3 GHz to 3.6 GHz. The tested PA performs a drain efficiency of over 40% in a back-off range of 7 dB and a gain about 12 dB in the operating frequency range. The peak output power is 43.5 dBm when tested by continuous wave (CW). R&S SMA200A vector signal generator generates a 20 MHz LTE signal with a sample speed 122.88 Msa/s, which has a peak to average power ratio (PAPR) of 7 dB. The average output power of PA is set to 32.0 dBm and 35.7 dBm. Signal receiver is spectrum analyzer R&S FSW 43 with 80 MHz observation bandwidth of intermediate frequency (IF) filter.

Iterative learning control is a convenient tool to evaluate the linearization ability of a behavioral model [28, 29, 30]. The ILC signal can be considered as an ideal DPD signal of the tested PA. After training the ILC signal of the DUT, three models (MP, GMP and MCVM) are employed to fit the ILC signal by the LS algorithm. Due to the observation bandwidth limitation, a band-limited modeling method by filter is applied [31, 32]. Because there are two measurements with different output power, the linearization results are given separately. The DPD linearization performance with 32.0 dBm output power is illustrated in Fig. 3. Details about the ACPR are given in Table I. With PA output power

Fig. 3 Spectrum of experimental results with a output power of 32.0 dBm.

Fig. 4 Spectrum of experimental results with a output power of 35.7 dBm.

Table I Model performance comparison when the PA output power is 32.0 dBm

ACPR (dB)	Alt lower	Adj lower	Adj upper	Alt upper	Coefficient number	NMSE (dB)
PA	-47.5	-36.0	-33.0	-42.4	-	-
MP	-54.4	-50.7	-49.0	-51.6	28	-40.7
GMP	-54.1	-54.8	-53.2	-52.2	175	-41.7
Proposed	-56.5	-55.2	-53.8	-53.9	168	-44.3

Table II Model performance comparison when the PA output power is 35.7 dBm

ACPR (dB)	Alt lower	Adj lower	Adj upper	Alt upper	Coefficient number	NMSE (dB)
PA	-43.5	-29.9	-30.5	-40.3	-	-
MP	-49.4	-47.6	-47.2	-48.4	28	-38.4
GMP	-52.7	-49.2	-50.0	-51.0	175	-42.0
Proposed	-50.6	-51.0	-52.5	-49.1	168	-42.8

of 35.7 dBm, the linearization results are given by Fig. 4 and Table II. From Fig. 3, Fig. 4, Table I and Table II, the proposed MCVM has better ACPR than MP and GMP. Compared with GMP, the MCVM has 0.6-2.5 dB improvement with the same level of coefficient number. The NMSE between the ILC signal and the modeled ILC signal by the three model is also given in Table I and Table II, which further proof the modeling ability of the proposed MCVM.

5. Conclusion

In this letter, a memory cross Volterra model is proposed for behavior modeling and linearization of RF PA with loop delay mismatch. In the simulation, a complex nonlinear system is built with nonlinear delay mismatch. Forward mod-

eling ability is evaluated by simulation. The performance of GMP and MP model are compared both in simulation and experimental results. The forward modeling ability and linearization performance of the proposed MCVM are better than GMP with the same level coefficients. For future issues, the performance of MCVM with other complicated systems [33, 34, 35] with nonlinear loop combinations can be studied.

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