Recent Progress in the Rolling Mills—Part I*

By Akio SUZUKI**

I. Introduction

In the great expansion of Japanese iron and steel industry to reach the world's third place in the crude steel production, our modernized rolling mills have made a significant contribution. The progress achieved by our universal slabbing mills, hot strip mills, cold strip mills, universal flange mills, and others was on the par with that won by other iron and steel making equipment like large blast furnaces, large oxygen converters and continuous casters. It was not only in the quantity that the progress was apparent but in such quality-intensive fields as the shape, materials, and precision of size that a great accomplishment was made.

It is true that the advent of computer control has aided greatly to labor saving and to operation stabilization as well as to the improvement of product quality just mentioned. But it is also true that behind the remarkable progress attained in the rolling productivity, there has been a close cooperation among the theoreticians, mill fabricators, electric machinery suppliers, and the steel producers in what I would call an organic combination of softwares and hardwares.

In this Nishiyama Memorial Seminar, I shall review the history of rolling equipment in general, then the peripheral technologies that have made those advancements possible, and finally I shall briefly survey the future prospects of rolling.

II. Progress of Rolling Equipment††

1. Improvements in the Productivity

It was to meet the enormously increased demand in supply and in variety of steels that enlargement of rolling work stocks like ingots, slabs, billets, hot coils was made, and increase of rolling speed as well as concatenation of rolling mills became necessary also. In keeping with those trends, improvement and development of rolling plants as a whole for better automation and sophistication were intensified to bring about markedly improved operation rate and labor saving. This resulted in simultaneous advancement both in the operation techniques and in the productivity. This is illustrated in Fig. 1.

1. Increase of Rolling Speed

The increase of rolling speed for the reversing mills like bloomers and plate mills were achieved by the use of the thyrister–leond controlling method, which made the quick returning readily possible, on one hand, and by the employment of large diameter rolls, on the other.

In the hot strip mills, it was largely due to increased slab weight that ensured greater rolling productivity and keeping of desired end temperature. To stabilize the product quality, on the other hand, fully continuous, rather than semi continuous, roughers became popular, though in recent years quasi-continuous three-quarter rougher train is being reconsidered for versatility.

For the finisher train, the number of tandem stands has been enlarged from 6 stands to 7. Further, with stiffening of rolls, roll bearings, and mills themselves on one hand, and with advances in AGC

Fig. 1. Progress of Japan's steel production (Statistics due to Ministry of International Trade and Industry).


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Chapter IV. Advances of Peripheral Technologies

Chapter V. Future Prospects of Rolling Equipment

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(automatic gage control) and shape control on the other, the speed of finisher final stand began increasing since about 1950, then hot strip mills with a speed of 1 300 m/min or more were built in succession since 1967. Today, the fastest rolling speed is over 1 600 m/min, a speed that is very close to the limit of cooling capacity of the strip. This state of affairs is shown in Fig. 2.

In the cold strip mills, the speedup was achieved by the use of the thyristor–leonard control at the main drive motor and by improving the roll bearings, the hydraulic press-down mechanism, and the rolling lubrication technology, the last including refinement of analysis of behaviors of lubricants and emulsions. The results have been a greatest rolling speed of 2 500 m/min.

Up-with-the-speed has also been the standing order for other rolling facilities like pickling, cleaning, recoiling, and skin pass. For example, in the pickling line, the changeover from sulfuric acid to hydrochloric acid, introduction of mechanical descaler, enlargement of pickling bath, and others have pushed the fastest speed up to 360 m/min.

In the wire rods mill, speed increase was won by laying out the mills more rationally. The rolling speed, which remained long at about 30 m/sec with continuous mills, became 80 to 85 by the advent of fully continuous mills. Today, a speed as fast as 90 m/sec is being contemplated. This remarkable acceleration owes its due to the block mill in the finish line, which was first installed in this country back in 1969. An additional merit of increasing of rolling speed has been the increased billet weight, which is now as much as 2 000 kg thanks to the reduced temperature drop during rolling.

The trend has been the same with pipe-making mills also. In the Mannesmann, for example, a boring speed of 60 m/min has been attained, this by making the boring angle more acute, the roll diameter greater, and revolution speed faster. In the lap welding pipe mill, a combination of 14 stand forge line and a sizer has made a speed of 450 m/min quite possible, while in the electric welding pipe mill, replacement of low frequency resistance welder by high frequency resistance welder, then further by high frequency induction welder has ensured a 160 m/min for 50.8 mm (2 in.) mill or 80 m/min for 101.6 mm (5 in.) mill.

2. Enlargement of Unit Work Stock

The enlargement and sophistication of rolling mills was not merely to improve the productivity, but also to meet the mounting demands for greater variety in the width, length, and thickness of the rolled products. This necessitated enlarging both the size and the weight of unit work, so much so that today's universal mills can all handle ingots weighing up to 40 t—there even is a mill on the design board that takes on 70 t ingots.

The mills themselves became larger naturally, and today the horizontal rolls that used to be 900 to 1 000 mm in diameter are now 1 350 to 1 400 mm, while the main drive motors of 14 000 kW class are not uncommon where 4 000 to 6 000 kW motors were once good enough.

Enlargement in width and weight has been most conspicuous for the heavy plates intended for ships, land structures, and line pipes. The width, which was up to 3 048 mm (120 in.) when the 4-high mills made their appearance, is now 5 500 mm (220 in.). With this widening, reduction and rolling load became much greater. This means a stiffer mill, and today there are mills with main drive motors of 8 000 kW twin, backup rolls of a diameter 2 400 mm, and roll stand housings of a column cross section 11 000 cm².

The enlargement of hot strip mills is most apparent in the change in weight of coil and in pound per inch width weight (PIW); in 1960, they used to be 30 t

![Fig. 2. Progress of rolling speed of hot strip mill.](image-url)
and 10 to 18 kg/mm, respectively, and today they are as much as 45 t and 20 to 29 kg/mm.

In the rougher, too, the capacity of the drive motor per stand is increasing rapidly. Moreover, the scale breaker that removes the primary scale is now mostly of the vertical roll type (VSB) rather than the horizontal roll type, and to receive the continuously cast stocks more and more, the VSB, and the rougher edger for that matter, is now popularly of the powerful overhead drive type.

The progress in other rolling equipment is such that, in the crop shear, for example, the thickness is now 40 to 45 mm rather than conventional 25 mm, and machines that are capable of shearing up to 80 mm are being planned. In the down-coiler, the maximum thickness has been increased from 12 mm to over 16 mm, and reels that are able to coil up plain mild steels of up to 25 mm thickness have been developed to serve in the production of high strength line pipe steels. For the grooming* line, on the other hand, feeders and levelers have been enlarged to perform the straightening and cutting of thick, more than 12 mm, coiled steels. Changes that took place in the hot strip mill are summarized in Table 1.

In the cold strip mills, the capacity of the main drive motor has been increased year by year in correspondence with the progressively enlarged and widened hot strip coil. One mill that was built in 1968 with 2 180 mm width and 40 000 kW total capacity main motor is the greatest both in the mill width and in the motor capacity.

Finally, the demand for pipes for oil wells and oil lines that became especially acute after the Oil Crisis has accelerated the enlargement of pipe-making apparatuses. For example, in the UO press type large diameter welded pipe making, a mill that produces pipes of outer diameter up to 1422.4 mm (56 in.) was installed in 1970, then another that produces ones up to 1 623.6 mm (64 in.) outer diameter started operation in 1974. The one common and outstanding feature of those mills is the very large capacity press of 50 000 t, which is most powerful in the world. In the spiral mills, one that manufactures pipes of 2 540 mm (100 in.) outer diameter with 25.4 mm wall thickness and 40 m long is working. Even while the electrically welded pipe mills today can handle works of up to 660.4 mm (26 in.) outer diameter, pipes of up to 406.4 mm (16 in.) outer diameter are being produced by the plug mills.

3. Concatenation

Concatenation of mills and continuous rolling have always been among the major objectives of research and development. The 4-high, 5-stand 1 425 mm cold strip fully continuous tandem mill that was commissioned in 1971 is one representative cumulation of such efforts.

The idea of fully continuous rolling had already been realized in an aluminum rolling mill as far back as 1960, but practicing different rolling schedules all continuously by welding together coils of different thickness and width end to end does merit a special citation. The continuous annealing of cold rolled strips, on the other hand, has been widely implemented in the tinned and galvanized steel lines, but for cold rolled sheets that demand good press formability commercialization has been difficult because of insufficient grain growth and softening. Recently, however, the fast advent of quench-overaging treatment has made continuous annealing a commercial proposition to replace the conventional batch an-

<table>
<thead>
<tr>
<th>Mill</th>
<th>Date of start</th>
<th>PIW (lbs/in)</th>
<th>Mill width (mm)</th>
<th>Reheating furnace</th>
<th>Rougher train*1</th>
<th>Number of stands</th>
<th>Main motor capacity (kW)</th>
<th>Maximum speed (m/min)</th>
<th>Number of coilers*3</th>
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<td>April, 1965</td>
<td>750</td>
<td>1 024</td>
<td>P 180×3</td>
<td>R₁ R₂ R₃ R₄ F₁</td>
<td>6</td>
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<td>2 250</td>
<td>WB 300×3</td>
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<td>H</td>
<td>Nov., 1971</td>
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<td>2 250</td>
<td>WB 380×2</td>
<td>R₁ R₂ R₃ R₄ F₁</td>
<td>7</td>
<td>75 800</td>
<td>1 627</td>
<td>2</td>
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</tbody>
</table>

*1 P: the pusher type, and WB: the walking beam type
*2 R₁: the reversing type, R2: the returnable type, and T: the tandem
*3 The parentheses figures are for the proximity coiler.

* The word "grooming" is proposed for conventional "finishing", because in the modern practice much more QC (quality control) activities are involved here than in ordinary finishing and inspection.
nealing in a bell jar type furnace. Those continuous annealers that integrate in themselves such auxiliary processes as electrolysis cleaning, skin pass temper rolling, and inspection and grooming have been commissioned successively in 1971 and 1972.

In the area of high flow strength materials like stainless steels, the traditional Sendzimir reversible mill is being replaced by tandem mills as problems of top threading, welding of high Cr steels and lubrication were solved. The 1 300 mm, 20-high, 4-stand tandem mill that became operational in 1969 is one example.

As for the shape mill, by its very nature of having to perform three-dimensional deformation the analysis of rolling characteristics was lagging behind the fast advancing plate rolling theories, but a recently developed technology of controlling the inter-stand tension at a value near zero has made true continuous mill to appear. The first such mill was a large tandem line that concatenated one rougher and two finishers built in 1971. Then, three intermediates and four finishers (all universal type) were made continuous by means of the motor current memorizing control method. This tandem mill is known for its high productivity, some three times that of old practice.

Other technologies that are famous for their great effects on energy saving are the hot direct rolling (HDR), in which bloomer is connected to hot strip mill by sending the red hot slabs directly, and the hot charge rolling (HCR), where the hot slabs are charged into the reheating furnace. In the present state of practice, the HDR remains 20 to 45 % and the HCR 10 to 20 % in application to the hot strip mill, but with the world energy situation showing no prospects of improving, fast spreading is forecast.

4. Technical Rationalization

Besides those sophistication of rolling mills for enlargement, acceleration, and concatenation, new technologies to cover the impending labor shortage have become important.

Those devices that have been seen in the bloomer are the driver of the vertical rolls, the quick changer for both the vertical and the horizontal rolls, and the cassetted knives for the shear, and also the manipulator, the ingot buggy, and the run table. In the grooming line, slab coolers of either the submerging or the spray type that were developed to shorten and simplify the process, while spot scarfing machines, and grinders that can be readily automated to replace the conventional hand scarfer are gaining rapid recognition.

In the plate mill shop, improvements are seen everywhere from reheating furnace to grooming line, but most noteworthy is the rationalized layout and the fast process computer.

In the hot strip mill, the quick roll changer is the most clearly advanced. Where the roll change used to be done with a porter bar or a C hook, today every one of the operating mills is equipped with an appropriate number of quick roll changers of either the side shift type or the turntable type so that several stands may be attended to simultaneously (Fig. 3). Other apparatuses of notable labor saving and quality assurance is the direct transfer line that connects the roll changer tables to the roll shop, the chock quick assembler, the roll automatic dressing machine, and the chock grinder.

In the hot down-coiler, there is one that is known as the proximity coiler which is installed particularly close to the finisher so as to shorten the threading time. Other improvements for shortening the threading time are seen in the guides, loopers, hot run tables, pinch rolls, and wrapper rolls; also the automatic marking machine and the automatic bundler have proved effective for labor saving.

In the cold strip mill as in the hot strip mill, shortening of roll changing time has been successfully achieved by introducing quick changers. Also, the fully automatic coil handlers at both the entry and the delivery sides and the automatic threading apparatus have made fast threading possible.

In the wire rods mill, which features multi-product, small lot production, marked improvement is seen in the roll exchanger for universal mill. In the stand changing type, in particular, the newly developed automatic coupler and spindle positioner have been instrumental in shortening the roll changing time.

2. Improvement in Quality

It was not only by the progress of mass production technology that we have achieved the world's supremacy, but those various advanced technologies for quality improvement have had a great deal to do with it. In the technologies for betterment of quality, besides those of rolling equipment, rolling theories, electric measuring and controlling devices, and lubrication, the computer technology must not be overlooked. By computer technology, I refer particularly to the stabilization of quality and assimilation of control information by the use of fast process computers.

In the gage control, enlargement of backup roll diameter, strengthening of mill rigidity by enlarging the roll housing columnar cross section, and thyristor—
The hydraulic press-down, which was first applied in 1964 to a reversing mill, was steadily improved until it started replacing the conventional electric press-down in the cold strip mill in 1968. The changeover was so successful that today not only all the cold strip mills of this country are of the hydraulic press-down, but invasion into the plate mills and hot strip mills has begun. That is, today we have an all-electric press-down in the cold strip mill in 1968. The progress in the hydraulic press-down was so successful that today not only all press-down in the cold strip mill in 1968.

In the cold tandem mill, a mill in which the mill rigidity can be controlled as desired in accordance with the rolling characteristics has made its appearance. Also, as a means to compensate for the changes in the characteristics of hydrodynamic bearing during acceleration and deceleration, dynamic control is being practiced. And, for this purpose, roller bearing is being tried on the backup roll bearings.

As for the shape control, after the earlier development of the roll bending method, development of shape detectors for automatic controlling is in the foreground today.

Other topics of more recent years are the 6-high mill of a special structure that claims to be able to give a much improved cross section profile and shape, the differential rolling method in which the upper and the lower work rolls are driven at a different speed making large reduction rolling possible, the walking beam reheating furnace equipped with new skid and extractor, the high pressure water jet descaler, the water spray method of rolling temperature control, the edge heater for slabs, and many others.

I submit that without those large rolling apparatuses, let alone the progress in the metallurgy and temperature controlling, our high quality plate steels of outstanding as-rolled low temperature toughness, to mention just one example, have not been given births to.

### III. Recent Rolling Equipment

As a result of intensive and extensive research and development and of operational know how accumulated over a long time, numerous rolling apparatuses have made their appearances one after another. They encompass from small equipment to an entire plant, but, for want of time and space, only several that appear to me to be worthy of special citation will be discussed here.

#### 1. Hydraulic Press-down

The hydraulic press-down, which was first applied in 1964 to a reversing mill, was steadily improved until it started replacing the conventional electric press-down in the cold strip mill in 1968. The changeover was so successful that today not only all the cold strip mills of this country are of the hydraulic press-down, but invasion into the plate mills and hot strip mills has begun. That is, today we have an age of hydraulic press-down.

This is due largely to the improvements achieved in the electrohydraulic servo valve, the pickup, and the control technique, the results of which have been the quick response, high precision control of roll position, the variable mill stiffness control, the compensatory control for acceleration and deceleration, the compensatory control for roll eccentricity, and the tension control in accordance with press-down, namely those delicate controlling that were not good enough with electric press-down.\(^{12-14,17,18}\)

#### 1. Progress in the Hydraulic Press-down

In Fig. 4, I have illustrated the evolution of the press-down mechanism. First came the mechanical servo type, in which the reference point was the position of the intermediate cylinder ram, which was detected by amplifying its displacement relative to the press-down cylinder by means of oil enclosed between them and was mechanically fed back to the press-down cylinder. In this method, though the maintenance was easy, the response was not too fast because of the limitation in the servo valve performance and necessarily elongated piping. Nevertheless, this method is being used even today for it is good enough for many applications.

Then, in 1968 to 1972, the tension, or the compression, bar type became popular. In this method, the roll gap is detected by the load cell built in the bar. Though the sensitivity was greater in the lower frequency range, the rather narrow control range due to limitations imposed by the length and rigidity of the bar and the complexity of the structure were the problem.\(^{15}\)

Since 1973, analogue detectors have been being replaced by such digital detectors as the magnetic scale type or the inductosyn type that are capable of determining position at a high precision with a resolution of 1 pm regardless of the gage length. Today, direct detection of the position of ram or chock is quite feasible with those detectors, and also the structure has been much simplified.\(^{17}\) Recently, the electronic scaling type that combines electrohydraulic servo valve and those digital detectors is making appearance as the most advanced hydraulic press-down control component.

Those are compared in Fig. 5,\(^{19}\) and are functionally classified in Table 2.\(^{11}\)

#### 2. Application to Various Rolling Mills

Adoption of the hydraulic press-down has been quicker and wider for the cold strip mills than for any other. Today, both the mechanical servo type and the electric scaling type are being employed, and with electric scaling types fast response such as 40 msec for step response and 15 Hz for frequency response has been achieved in the roll position control.

In the plate mill, too, hydraulic press-down is being employed by recent mills, because the high load, high speed AGC rolling demands such mechanical stiffness and very fast response that the electric press-down cannot meet. That is to say, in heavy plate rolling, because of the large irregularity in the thickness of incoming plate arising out of the temperature irregularity at the skid marks, high speed and large reduction rolling is a necessity. For this, the flow rate through the servo valve need be large, meaning large capacity servo valves and a large oil.
reservoir. So much so that a heavy plate mill hydraulic press-down that was commissioned recently is equipped with a 300 kg/cm², 800 l/min high pressure servo valve and 1 600 to 1 650 mm diameter, 5 000 to 6 000 t cylinders for AGC.

The situation is much the same in the hot strip mill as in the plate mill, and here again adoption of hydraulic press-down has already begun.\(^1\)

2. Power Down-coiler

The upper limit of a hot strip mill product gage is practically determined by the down-coiler, whose

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**Table 2. Functional classification of hydraulic press-down.**

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<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
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<tr>
<td>Mechanical servo type</td>
<td>Feedback from cylinder ram</td>
</tr>
<tr>
<td>Compression bar type</td>
<td>Indirect sensing</td>
</tr>
<tr>
<td>Ram position detecting electric scaling type</td>
<td>Feedback from intermediate cylinder piston</td>
</tr>
<tr>
<td>Chock position detecting electric scaling type</td>
<td>Analogue measurement</td>
</tr>
<tr>
<td></td>
<td>Compression bar + Load cell</td>
</tr>
<tr>
<td></td>
<td>Tension bar + Load cell</td>
</tr>
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<td></td>
<td>Differential transformer</td>
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<td></td>
<td>Inductosyn</td>
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<td>Magnescale</td>
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ability is expressed in terms of the mandrel axial torque, which is continually on the increase as shown in Fig. 6. As may be seen here, the progress has been very rapid, and in 1968 a down-coiler of 9.4 t-m made its debut, making coiling of 19 mm gage plain carbon steel possible. Since then, increased demand for high strength line pipe steels had accelerated the progress, and the years after 1971 have seen the emergence of machines of mandrel torque of over 13 t-m, namely, the so-called the power down-coilers. With those coilers, making of coils out of mild steels of up to 25.4 mm is quite feasible and the range of products of hot strip mill has been expanded enormously.

I wish to discuss those power down-coilers in comparison with conventional ones in the following.

1. Mandrel

Generally, the down-coiler mandrel is of the 4 segment, hydraulic expansion type, of which the expander is either of the link mechanism or the wedge mechanism. Recently, however, the 3 to 5 wedges type is gaining popularity for its potency against segment deformation and pin wearing. In the power down-coilers, on the other hand, though their mandrels are not much different structurally from the conventional, internal forced-cooling is practiced to prevent the segment from deforming under regenerating heat.

2. Mandrel Driver

A large torque is necessary to coil up a thick strip, but then the high torque mandrel is unfit for thin strips because troubles like necking are apt to occur. Therefore, the power down-coilers are equipped with a switchable reduction gear so that low speed, high torque drive for heavy gage works and high speed, low torque drive for light gage stocks may both be practiced. Figure 7 shows some ways of choosing the high or the low torque drive.

3. Pinch Roll and Wrapper Roll

As the torque need to bend a strip at a pinch roll is proportional to a square of the thickness, the drive motor must correspondingly be large to handle heavy gage strips. In recent year, the power down-coiler motors have progressively become larger, and the greatest is as big as 1 000 kW (Fig. 8).

A large press-down force is needed for the wrapper roll of a power down-coiler also, because the wrapper is expected to work to help bend the strip. And, as it is subjected to a great impact when receiving the strip and when the second strip comes into overlapping on the first, the diameter of wrapper roll is necessarily large. Therefore, that is equipped with a shock absorber to improve the response at the same time.

4. Controlling

The feature of mandrel control at power down-coilers is the controlling of the maximum torque for the reel and that of bending torque. The maximum torque reel control is to maintain the tension constant while utilizing the motor power to a greatest extent to develop the large tensile force needed to reel in a very thick gage strip, whereas the bending torque control is to change the bending force in accordance with the increasing coil diameter so as to maintain the tension constant, all depending upon the properties of the thick strip being reeled in.

3. High Speed Pickling

The use of hydrochloric acid in large pickling line
dates back to M. Clouth Co.'s tower pickling line of 1963, and in this country it is rapidly spreading since a horizontal pickling line that had a built-in acid recovery unit was installed in 1966. Since then, many improvements have been done in raising of speed, automation, labor saving, and environmental protection, and today, 31 out of operating 42 pickling lines are using hydrochloric acid, of which one boasts a capacity of over 120 kt a month.

1. Speed-up, Automation, and Labor Saving

In Fig. 9, the changes in the pickling line speed are shown by the central part speed.\(^{21}\) The increase of speed after 1965 to the present level of 360 m/min is quite remarkable, and this owes to the increased descaling rate on changing from sulfuric acid to hydrochloric acid, enlargement of the bath, increased amount of immersed steel, and improved component apparatuses.

To meet the much increased coil weight, which today amounts to 45 t at the entry and 60 t at the delivery ends, further, various refinements in automation have been made for optimum control and labor saving. The more noteworthy ones are as follows.

1) Coil Handling Facilities: coil transfer machine, threader, automatic welder, side guide width setter, automatic bundler, and automatic deceleration and stop
2) Controllers: computer control (Table 3), loop controller, acid pH controller, and automatic weigher
3) Inspection and grooming facilities: crownmeter, widthmeter, lengthmeter, and surface flaw detector

(1) Scale Breaker

Earlier on, the scale breaker is often omitted in the hydrochloric acid pickling lines, but this is being reconsidered as the secondary scale breaker is gaining popularity for its effect of restoring the descaling efficiency, which has been on deterioration under the prevailing high temperature reeling-in practice.\(^{22}\) The scale breaking, which is performed by straining the strip surface, is analyzed in Fig. 10.\(^{23}\) from which the popularity for the bending/tensile method and the skin pass rolling method may be understood. An example of usage in an actual line, where the bending/tensile method is practiced in front of the pickling bath, is illustrated in Fig. 11. It is said that

![Fig. 9. Progress of pickling line speed (at the central bath).](image)

![Fig. 10. Comparison of various methods of scalebreaking.](image)

![Table 3. Functions of computer control.](image)

*APC: Automatic position control
the effect of scale breaking is equivalent to some 10% increase in the pickling rate.\(^{24}\)

On the other hand, the mechanical descaling, that does not use any acid at all, is approaching commercialization. One such apparatus is illustrated in Fig. 12 for its operating principle and in Fig. 13 for the system.\(^{25}\)

(2) Temperature and Concentration Control

The rate of pickling depends very much on the acid concentration and temperature as shown in Fig. 14. Of the two, the acid concentration is controlled by the quantity of the recirculated fluid, and here a method in which the recirculatory flow rate is controlled as a function of the surface area of the strip to be pickled and is corrected by automatically determining the iron content of the waste acid overflowing the bath.\(^{26}\) This method is known to ensure an optimum operation and an increased pickling rate.

The heating of the acid, which is being done commonly with steam, can be either direct or indirect. That is, the steam may be injected straight into the bath or be used as the working medium of heat exchanger. In the latter, the out-of-the-bath method, in which the acid is led to the heat exchanger located outside of the bath, is becoming popular.

Other innovations of note for energy saving and prevention of acid hume pollution are the floating lid and the intermediate cover, which is placed inside the ordinary bath cover, and both are said to be worth some 7 kg/t saving in the steam rate.\(^{22}\)

3. Curtailment of Downtime at Entry and Delivery Ends

(1) Automatic Welder

To improve the commonly used flush butt welder that needs the work to be cut, welded, and trimmed at different positions along the line, a new type automatic welder is in the offing.\(^{27,28}\) This machine has a built-in shear, so that those three operations are conducted at the same position on the two strips that are clamped end on end, and some 30 precious seconds are saved.

(2) Loop Accumulators at Entry and Delivery Ends

For the strip accumulation at entry and delivery ends, the loop car type is common, and usually 2 to 3 stages are provided beneath the pickling bath. Further, as may be seen in Fig. 15, the amount of accumulation has been on the increase as the line speed is.

4. Spray Cascade Rinsing

Rinsing is performed at the delivery end of the pickling bath, where the amount of spray water had to be increased as the line speed was increased, and
today in some lines it is already over 100 m³/hr. To save on the water, the cascade rinse method that permits of the use of recirculated water is commonly adopted. In the system shown in Fig. 16, the quantity of fresh water that is to make up at the last tank is no more than about 10 m³/hr, while the waste water that overflows the first tank is of an iron content of about 80 g/l with an acid concentration of about 2 %. This makes the acid recovery easy.30,31)

4. Fully Continuous Cold Rolling Mill

The fully continuous rolling, which was first advocated by Lenze in the 1960s, was realized in the aluminum rolling and with Sendzimir mill in the special steel rolling. However, the world's first truly fully continuous mill, that is, in the meaning of that the mill is capable of taking different width, different gage coils of mild steel without interruption, is the 1425 mm, 5 stage tandem mill that was commissioned in 1971. This mill is a culmination of long experiences refined in the conventional tandem mills and various newly developed technologies. As the continuous mill promises improved productivity, yield, and quality, as well as labor saving, at a certain expense in the capital investment, it is steadily gaining popularity since its appearance.32–35)

1. Formation of the System

The equipment system of computer controlled fully continuous cold rolling mill is exemplified in Fig. 17.

1.1 Equipment for the Rolling Mill

Though the rolling mill itself is not much different from the conventional tandem mill, special features are seen in the entry and the delivery equipment.

1.1.1 Entry End Equipment

To carry on the rolling operation even while the strip is stopped for welding of the succeeding coil, loop car type accumulator is provided. The designing of the accumulation should be done on the weight of coil, welding time, rolling speed, and production rate desired to be the most economical. Examples are shown in Fig. 18.

As the welded joint is an important demarcation to define the coil-to-coil junction and the point of change of gage control for the flying strip, it need

![Fig. 15. Relation between line speed and loop capacity.](image)

Effective loop length: Usually limited to 80~90% of the rated maximum accumulation to protect the apparatus.

![Fig. 16. Structure of cascade rinse line.](image)

Spraying of recirculated water is done at every bath.

![Fig. 17. Fully continuous cold strip mill line and computer control system.](image)
be detected precisely at the entry end of the line. For this, the magnetic permeability detection method and the magnetic marking method are available.

(ii) Mill Proper
As such troublesome works as threading or tending to the runaway strip are no longer necessary, the threading guides that crowd the stand at the entry side are all but eliminated, and the merit of simplification is considerable. Further, the mill housing and the roll chock are specially designed so as to make the work roll change easy and quick.

(iii) Delivery End Equipment
Here, the strip is sheared while flying and fed alternately to the proper one of the pair of the down-coilers, by means of the selector gate, keeping the rolling speed at over 250 m/min. For this, devices to prevent the lancing or buckling are provided.

(2) Computer Control
The computer controlling is indispensable with a fully continuous cold rolling mill. The functions expected of the process computer are summarized in Table 4.

(i) Coil Tracking
Continually following the flying strip, the computer tracks out the progress of rolling by detecting the pickled welded part and the mill welded part, determines by computation points of the gage change and shearing point, and issues out an appropriate action command.

(ii) Flying Alteration of Gage and Width
This is a technique that allows the pass schedule to alter and the strip gage to change suddenly, and is the most important among the functions of computer. For this, the dynamic chronological alteration actions must be executed precisely in accordance with the computations done in advance.

Table 4. Functions of control computer.

<table>
<thead>
<tr>
<th>Action</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Coil tracking</td>
<td>Tension control</td>
</tr>
<tr>
<td>Leveler gap setting</td>
<td>Droop setting</td>
</tr>
<tr>
<td>Side guide position setting</td>
<td>Roll bender setting</td>
</tr>
<tr>
<td>Welder setting</td>
<td>Flying shear operation</td>
</tr>
<tr>
<td>Strip accumulator control</td>
<td>Automatic lap check</td>
</tr>
<tr>
<td>Flying alteration of gage and</td>
<td>Operation record and data logging</td>
</tr>
<tr>
<td>width</td>
<td>CRT display</td>
</tr>
</tbody>
</table>

2. Features of Fully Continuous Cold Rolling Mill
As mentioned a little earlier, the greatest merit of fully continuous mill lies in the freedom from troubles of threading and runaway strip. From this, and aided by the computed control, many features are derived.

For example, thanks to this freedom, the downtime is very much cut short and the damage to rolls decreased, remarkably improving the per tonnage rolled steel rate of roll consumption and needing very much less number of attending crew. All those, and the shortened time of rolling a coil, have improved the productivity greatly, as much as 1.5 times. Some factual results are shown in Fig. 19.

For another, thanks to the computing control, the amount of off-gage, though inevitable at the junctions of a coil to the next, is remarkably decreased to one fifth of conventional mill's as shown in Fig. 20. Also, because the tension can now be imposed on the strip all along its length, and thanks to the continually jetted coolant, not only the thermal deformation of the rolls has been practically eliminated and the strip shape stabilized, but the fluctuation of the temperature of rolling oil and of oil tank level is all but erased as may be seen in Fig. 21.

The less salient but equally important feature of
going to full continuous is the improvement in the work environment. That is to say, almost all the crew are now stationed in the central control room simply because there is very little they have to attend to on the floor.

5. The 6-high Mill

Owing to the advancements achieved in AGC, the precision of strip thickness was improved greatly. The control of the shape, however, still remained dependent on the operator's skill because detection and controlling of it for the flying strip was not yet possible; it is only recently that a number of shape detectors and controlling methods have emerged.

To improve on this, several rolling mills have been developed. The more famous ones are the MKW (Mehrwalveyem–Kalt–Walzwerke) mill, the 6-high mill, and the double chock bending mill. Of those, in the light of the two most important functions of shape control, namely, the shape stabilizing function, and the shape correction function, the 6-high mill is drawing a great attention.

1. Outline of the 6-high Mill

In a common 4-high mill, that portion of the work roll which extends out of the breadth of the work piece is subjected to additional bending moment, which gives rise to a large flexure in the work roll. Further, the bending effect of the work roll does not reach sufficiently well to the central part of the roll because it is under restraint of the backup roll to very near the ends. The 6-high mill, known as the HC, or the high crown control, mill, has been devised to solve this problem.

The idea of the HC mill was first verified with a small research mill, then in 1974 to 1976 it was tried out on a reversing mill. In 1977 to 1978, further, one of the fore or the rear stands of a high speed 6-stand mill was fitted with this 6-high rolls designed specifically in accordance with the requirements of rolling. It was duly confirmed that the 6-high mill had features the ordinary 4-high mills did not possess.

2. Principles and Structure of the 6-high Mill

As illustrated in Fig. 22, in this 6-high mill a pair of intermediate rolls are provided between the work roll and the backup rolls. These intermediate rolls can be shifted sideways, namely in their axial direction, so as to position their ends in accordance with the width of the work piece. Thanks to this, the work roll is disengaged at outside the work from the contact with the backup roll, so that it is no longer subjected to the effects of the backup roll's bending moment at its ends. This makes the flexure of the work roll markedly smaller to improve the shape of the work piece, and, at the same time, makes the effect of bending of the work roll much augmented to be able to obtain flatness for a wide range of strip width with zero initial crown for the work roll.

Those effects of the intermediate rolls are apparent in the 6-high mill's ability of taking greater reduction, the smaller diameter work roll, no need of providing the initial crown, marked decrease of edge drop, and others. As its superiority over conventional 4-high mills is very clear, it is being used in the skin pass mills as well as in the cold strip tandem mills, and introduction to hot strip mill is being contemplated.

6. Continuous Annealing Line

The making of cold rolled sheet steels of deep drawing grade for automotive or electric home appliances use has long been a time-consuming work: it has to go through electrolysis cleaning, batch annealing, cooling of coil, temper rolling, and inspec-

Fig. 20. Actual examples for chart record of flying gage change.

Fig. 21. Actual records of states of coolant.
tion and grooming. Of those, the batch annealing had for some time been replaced with continuous annealer when making tinned or galvanized sheets, which require no particularly good formability.

For deep drawing steel, however, the material has to go through quick heating, then, in close succession, hardening by quenching. It was the difficulty of meeting those two metallurgical requirements as well as another one of equipment technology, that of concatenating those five independent processes into one and single apparatus, that had been holding the progress up for a long time.

This very difficult proposition was finally realized in a form of fully continuous annealing line, and several of them were developed and installed successively in 1971 and 1972.

1. Outline of Continuous Annealing Line

The representative of the continuous annealing lines are the CAPL and the NKK-CAL, which are respectively shown in Fig. 2341) and Table 5.42) In short, they are composed of, from the entry end towards the delivery, the electrolysis cleaning unit, the furnace unit, the temper rolling mill unit, and the inspection and grooming unit.

(1) The Front End

In the front part, the cold rolled coils are welded together one by one and fed, with the lubricant oil removed, into the furnace part as one continuous strip at a constant speed. It is composed, as shown in Fig. 23, of a pair of pay-off reels, a welder, an electrolysis unit, and an intake looper. To execute the coil change in a minimum possible time, the pair of pay-off reels is activated alternatively, and the narrow lap seam welder ensures a good joint that takes many bendings to be given by the hearth rollers through the line. The time needed to switch the reel is about 40 sec.

The electrolysis cleaning unit is composed of the chemical cleaning in an alkaline bath, the mechanical cleaning with brush rolls, and an electrochemical cleaning bath. The cleanser is ortho sodium silicate, and the electrolysis power source is of about 120 kVA capacity.

(2) The Furnace Unit

In the furnace unit, the strip goes through five zones of the primary heating, the homogenization, maintained by electric resistance heating, the primary cooling, the overaging, the reheating, which is done either by electric resistance or by radiant tube, and the secondary cooling. The typical heating cycles of CAPL and NKK-CAL are shown in Fig. 24,41,42) In the overaging treatment, which is one important process in the entire continuous annealing, the strip is quenched to below 500 °C so as to supersaturate the dissolved carbon, then reheated and kept to 300 to 450 °C to have the once dissolved carbide finely reprecipitated. The major difference between the CAPL and the NKK-CAL lies in the method of quenching in this primary cooling, in that the CAPL uses gas jet, whereas NKK-CAL relies on water quenching. The furnace atmosphere is a mixture gas of hydrogen and nitrogen for either, and the hydrogen content is usually 2 to 7 %.

The heating zone is designed to heat the strip up to 900 °C, and the heater is radiant tubes burning coke oven gas with a thermal input of 12 000 to 16 000×10⁳ kcal/h.

In the homogenization zone of CAPL, a 3 000 kW electric heater is provided to keep the strip warm and to facilitate the heating of furnace after stopping of the line.

The strip temperature control, which had to be done on the basis of furnace temperature because of difficulty of measuring the strip temperature directly, should really be done by the temperature of strip

| Table 5. Major specifications for CAPL and NKK-CAL. |
| --- | --- |
| | CAPL | NKK-CAL |
| Objects | Cold rolled low carbon strip steels* | Ditto. |
| Thickness (mm) | 0.4～1.2 | Ditto. |
| Strip width (mm) | 750～1 240 | 610～1 300 |
| Coil weight (t) | 45 max | 32 max. |
| Line speed (m/min) | 200 | 180** |
| Furnace capacity (t/h) | 60 | 60 |

* Includes JIS SPCG (the general purpose grade), SPCD (the drawing grade), and SPCE (the deep drawing grade).

** The speed through the furnace, at entry 225 m/min and at exit 250 m/min.
itself to ensure the quality. For this, an automatic direct strip temperature measuring control system has been invented for the CAPL, while a reference plate comparison method has been developed for the NKK-CAL. Those methods are illustrated in Figs. 25 and 26, respectively.

In the primary cooling zone, in which cooling of strip to the overaging temperature is conducted, a rate of 5 to 30 °C/sec is achieved in CAPL by gas jet blown through water jacketed nozzles. In the NKK-CAL, on the other hand, very fast cooling rate of over 2 000 °C/sec is assured on water quenching, shortening the time of overaging treatment appreciably. Here, the perfection of spray technique that does not deform the strip has been the key point.

For overaging, the strip temperature may simply be kept at a prescribed temperature in the CAPL, for which purpose a 4 500 kW electric heater is provided. In the NKK-CAL, on the other hand, the strip has to be reheated following the water quenching, and for this purpose radiant tubes are provided for a thermal input of up to 9 000×10³ kcal/h.

The secondary cooling is done by the gas jet, the atmosphere being cooled by water cooling or with a refrigerator so as to have the strip cooled to 40 °C and be fed to the temper rolling with no further ado.

The overall length of the strip within the continuous line can be as long as 800 to 1 000 m, and to prevent it from snaking, a number of steering rolls for centering are strategically provided. Also, as the strip is
delicately stretching or contracting all differently under different heating and cooling states through those zones, the tension control is done independently for each zone.

(3) The Rear End
In the rear part, the dead soft annealed strip is given a light temper rolling to regulate its mechanical properties, groomed by trimming the sides, inspected, sprayed with oil, then coiled to a specified weight. For this, a takeout looper, a temper rolling mill, a pair of side trimmers, an oiler, a shear, and a pair of downcoilers are provided. To minimize the downtime at the outlet, the trimmer and the tension reel are provided by the pair besides a quick roll changer. Also, coils can be divided by the flying drum shear without making the succeeding strip to pause.

2. Appreciation of Continuous Annealing Line
The continuous annealing line technology is characterized not only by successful concatenation of five independent processes from electrolysis cleaning to grooming, but by the thorough rationalization of labor and redundant or overlapped works. A comparison with conventional method is shown in Table 6, where a great labor saving, energy saving, and cutting down of costs may be appreciated.

Besides those merits, because the continuous annealing line permits of a large flexibility in the heating rate, the heating temperature, and the cooling rate of the strip being treated, extensive application to making of high strength sheet steels and other new products is being held in good prospect.

7. Recent Reeling Equipment—Continuous Reel-in and Reel-out Machine for Strip-making
To keep pace with the automation in rolling and grooming processes, automation and continuation of pay-off and down-coiling of coils is indispensable. A number of apparatuses have been invented for this purpose, and the carrousel type reel is one of them.

1. Features of the Carrousel Reel
As may be seen in Fig. 27, the carrousel reel features the two bobbins provided on a revolving disk, one of which is at the service position either as a downcoiler or as a pay-off reel, while the other is at the waiting position, or 180 deg off phase, taking out the wound coil or being prepared for receiving or paying off the next strip coil.

The greatest merit of using this machine is found in the greatly reduced work time, which is now less than one half of the conventional case as seen in the time schedules compared in Fig. 28. The second
feature is the ease of coil handling, in that, as illustrated in Fig. 29, the paying off can be started directly from the top end handling position, which is higher than ordinary to afford good observation by the operator for both taking-in and taking-out of a wound coil. The third advantage is the smallness of the area needed, which is about one half of what the conventional twin reel equipment would occupy, though in the total cost they may not be too much different.

2. Solving of Technical Difficulties

As the carrousel reel itself is large and holds large components that rotate at a high speed, various problems like the resonant vibration of the drum had to be, and were duly, solved. For example, as the revolution of carrousel disk affects on the tension imposed on the strip under coiling-down or paying-off, a special revolution control that keeps the tension constant and minimizes the shock to the strip on stopping of the disk has been added. Also, to feed the work oil (70 kg/cm²) into the carrousel disk and the lubricant oil (5 kg/cm²) to gears and bearings, all from the ground to the rotating body, a large universal joint was newly developed.

8. Continuous Rolling of H Steels

The H steel, which was first manufactured in this country in 1961 by the caliber rolling method, has been on increasing demand for uses in structures that were becoming larger and higher-rising for their large sectional moment and ease of handling.

The rolling of H steels, however, proved to be more complex than the plates. Yet, as theoretical analysis conducted on a research mill made fast progress, so did the computer control technique advance. The results have been the emergence of the semi-continuous mill, then of the fully continuous mill, replacing the conventional reversing mill. Figure 30 gives a comparison of those three mill layouts.

1. Features of Fully Continuous Shape Rolling

It is true that even today the H steels are being rolled by the universal mill aided by reversing edger, but in comparison with this practice, the continuous mill can boast markedly improved productivity on larger per pass reduction, greater products dimensional precision due to unvarying rolling conditions, and the manufacture of thinner gages due to higher finishing temperature. To develop those features fully, however, the interstand flying speed of the work stock must be controlled precisely. And, as the loop rolling, which is quite feasible with wire rods and small sections, cannot be applied to large sections, occurrence of tension or compression in between the stands is inevitable. Since this force can be an immediate cause for misrolling and damages to the equipment as well as can cause a large fluctuation in the product dimensions, a control system that holds the tensile or compressive force arising out of unbalanced material flow between two stands to zero, or at least to a minimum, has been in urgent need.

2. Controlling of Continuous Mill

The H steel rolling by universal mill has been extensively studied by means of plasticine experiments and by analyzing the data of operating mills, and also the effects of small diameter vertical rolls on the dimensional precision of products were subjected to strenuous study. It was indeed on those researches that fully automatic continuous mill was commercialized.

Now, the ultimate purpose of continuous rolling is, as may be seen in Fig. 31, to equalize the volume

<table>
<thead>
<tr>
<th>Actions</th>
<th>Conventional reel</th>
<th>Actions</th>
<th>Carrousel machine</th>
</tr>
</thead>
<tbody>
<tr>
<td>Drum closed</td>
<td></td>
<td>Upper pinch roll</td>
<td></td>
</tr>
<tr>
<td>Coil car traversing</td>
<td></td>
<td>Lower pinch roll</td>
<td></td>
</tr>
<tr>
<td>Drum opened</td>
<td>17 (400 mm @ 200 mm/sec)</td>
<td>3 (500 mm at 100)</td>
<td></td>
</tr>
<tr>
<td>Coil car lift lowered</td>
<td>2.5 (400 mm @ 100 mm/sec)</td>
<td>1.5 (500 mm at 17.5 m/min)</td>
<td></td>
</tr>
<tr>
<td>Threading</td>
<td>1.5 (500 mm at 100)</td>
<td>3 (500 mm at 100)</td>
<td></td>
</tr>
<tr>
<td>Pinch roll engaged</td>
<td></td>
<td>17 (4000 mm @ 17.5 m/min)</td>
<td></td>
</tr>
<tr>
<td>Threading</td>
<td>17 sec</td>
<td>10 sec</td>
<td></td>
</tr>
<tr>
<td>Strip passed through</td>
<td>2.5 (400 mm @ 100 mm/sec)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Drum closed</td>
<td></td>
<td></td>
<td>the same as left</td>
</tr>
<tr>
<td>Coil car lift raised</td>
<td>1.5 (500 mm at 100 mm/sec)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Drum closed</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Coil car traversing</td>
<td>7.7 (4000 mm @ 2000)</td>
<td>7 (4000 mm @ 2000)</td>
<td></td>
</tr>
<tr>
<td>Drum opened</td>
<td></td>
<td>7 (4000 mm at 2700)</td>
<td></td>
</tr>
<tr>
<td>Belt wrapper advancing</td>
<td></td>
<td>26 sec</td>
<td></td>
</tr>
</tbody>
</table>

Fig. 28. Comparisons of temper mill reeling time schedule between conventional and carrousel.
metric velocity of the steel at each stand so as to obtain products of invariable dimensions. For this, the deformation behavior under tension and the loading characteristics of the steel have been clarified by experimentation in a research model continuous mill, in which the adaptability of lead as a simulator material was established. This led to development of a mathematical model to enable calculation of the coefficients for tension between a given pair of stands, the transition between tensile and compressive states, the effects of such extrinsic perturbations as skid marks, thermal run-down, and ripples in the electric current, and the advancements or retardations. Those studies gave foundation to the subsequent development of the AMTC (automatic minimum tension control), in which the motor current or the rolling torque is detected for controlling. Also, the interstand distance has become determined on consideration of the time of impact drop and that of occurrence of tension. Then, an advanced controlling, in which the rolling speed is corrected even for speed changes during impact drop or passing through, has been developed and actually used. Figure 32 shows an effect of AMTC in terms of the changes in the flange width.

3. An Example of Continuous Rolling Mill

In Fig. 33, the layout of the world's first regular
service fully continuous H rolling mill that was commissioned in 1972 is shown.47,52,54) It is known for such features as:

(1) the great productivity, in that the mill is capable of manufacturing 80,000 t/month against conventional mill’s 50,000 t, yet having a ready margin of expansion to 14,000 t;

(2) the rougher train, which is composed of 4 roughers of $R_a$, $BD$, $R_1$, and $R_2$, the roughers being the once-through type and the breakdown mill the reversing type;

(3) the unique full automation on the AMTC, in which the intermediate train comprises three universal mills and the finishing train four universals and two edgers, all in tandem;

(4) the very fast roll change, in which the rolls and guides are cassetted for the quick three-position exchanger machine,55 while for the intermediate and finisher stands, double change type stand exchange is practiced with the electric lines and the hydraulic pipes all instantaneously attached or detached by autocoupler; and

(5) the on-line controlled grooming line, in which the long (130 m) cooling bed, the long straightener, and the cold saw that can attend to several pieces in quick succession are controlled by a process computer, which also commands the sizing, stamping, classification, and bundling to carry the stock continuously into an automatic three-dimensional warehouse, which is, in its turn, fully automated from reception to shipping by a computer.

9. High Speed Rolling of Wire Rods—The Block Mill54,55)

What is so remarkable with modern wire rods mills is the adoption of the block mill in the finishing line, and this has been spreading fast since 1969. Owing to the block mill, the finishing speed, which remained at about 30 m/sec, was increased to 80 to 85 m/sec, and simultaneously with this, products of good dimensional precision and free from surface defects became to be had easily.

Of the block mills, the first was Cox’s three rolls mill, followed by Morgan’s No-Twist Mill, then Schlömann’s and Demaag’s, subsequently Mehler and Neumann’s and Ashloe’s joined force. Here, the features and advantages of block mill is presented with Morgan No-Twist Mill as an example.

The most fundamental difference to conventional finisher mills lies in the rolls and the roll drive mecha-
nism, which are illustrated in Fig. 34 and compared in Table 7. Namely, the rolls are made of tungsten carbide for good durability, of the cantilever type to dispense with conventional mill spindles and couplings, which are the known sources of vibration, and are set in a frame in tandem, mutually inclined 45 deg to the horizontal plane to cancel out the twisting. Though the caliber is only one to four to a roll, caliber change is easy because it is done by changing the rolls themselves by the frame. Also, as all the rolls are driven by a common drive with forward tension imposed, the awkward loop control is no longer necessary, making the line control considerably easier.

The second feature is found in the bearing, for which the three-layer slide bearing of Cu-Pb alloy base metal is revived. An example is shown in Fig. 35.

The third is the lubrication, which is of a highly sophisticated one as may be seen in Table 8. This is to withstand the very severe lubrication conditions that come from the high speed, heavy load rolling. A special oil that is not only corrosion preventive but combines the characteristics of hydrodynamic lubricants and of gear oils has made its appearance recently.

![Fig. 34. Roll drive mechanism of the block mill.](#)

![Fig. 35. Bearing for the block mill.](#)

### Table 7. Comparison between block mill and conventional mill.

<table>
<thead>
<tr>
<th></th>
<th>Block mill</th>
<th>Conventional mill</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Rolls</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Support</td>
<td>One end supported</td>
<td>Both ends supported</td>
</tr>
<tr>
<td>Material</td>
<td>WC (Tungsten carbide)</td>
<td>High alloy, chilled or grain</td>
</tr>
<tr>
<td>Hardness (H_{s})</td>
<td>95~98</td>
<td>80~85</td>
</tr>
<tr>
<td>Life of finishing caliber (t/caliber)</td>
<td>300~500</td>
<td>50~70</td>
</tr>
<tr>
<td>Shape and dimensions</td>
<td><img src="#" alt="57~72 mm" /></td>
<td><img src="#" alt="250~300 mm(d)" /></td>
</tr>
<tr>
<td>Finishing speed (m/sec)</td>
<td>80~85 (for 5.5 mm(d))</td>
<td>a(d). 35 (for 5.5 mm(d))</td>
</tr>
<tr>
<td>Areal reduction per stand (%)</td>
<td>18~22</td>
<td>15~19</td>
</tr>
<tr>
<td>Change of caliber</td>
<td>By the rolls</td>
<td>By using a different caliber of the same roll</td>
</tr>
<tr>
<td>Mechanism of pinion and roll drive</td>
<td>Rolls are set at the end of the pinion stand</td>
<td>Connected through coupling and spindle</td>
</tr>
</tbody>
</table>

10. **Direct Patenting**

Wires are rarely put to services as rolled, but generally they are submitted to a heat treatment known as patenting before use. This process is ordinarily conducted in an independent patenting furnace, but a method that utilizes the steel’s sensible heat to achieve an effect almost equivalent to that by controlling the cooling rate right on the rolling line has been developed. This process is called the direct patenting.

As this method is well suited for handling large coils (1,500 to 2,000 kg) to keep up with the high rate production of high speed mills, the method of controlled cooling, which is the central point in the direct patenting, has been a subject of intensive development. The first that emerged was the Stelmore Process, which was commercialized in 1964. In this method, the wire is quenched to about 800 °C, then laid out on a belt conveyor in a series of eccentric loops, and control-cooled by air jets blown from under to below about 400 °C. This is illustrated in Fig. 36.

Subsequently, various other methods have been devised. The more famous ones are the vertically
descending conveyor method, the fluidized bed cooling method, and the boiling water cooling method. The working principles are shown in Figs. 37, 38, and 39, respectively, and their features are summarized in Table 9.

It is well appreciated that the direct-patented stocks are of a refined pearlite structure, which is uniform all through the entire coil, and therefore of a good drawability and good mechanical properties that are comparable to, or often even better than, those of air patented wires. However, when compared to the lead bath patented wires, which are the best in quality, the direct-patented stocks are inferior in strength and in uniformity of quality. This is shown in Fig. 40 by comparing the drawability between the conventionally cooled wires and direct-patented ones, and again in Fig. 41 by comparing tensile strength among the lead bath patented, direct-patented, air patented, and conventionally cooled wires.

Though a considerable progress has been made, the direct patenting needs further development before it is accepted universally by all the mills.

(continues to Trans. ISIJ, 24 (1984), No. 4 (April))

Table 8. Comparison of lubrication system between block mill and conventional mill.

<table>
<thead>
<tr>
<th></th>
<th>Block mill</th>
<th>Conventional mill</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Line filter specification</strong></td>
<td>10~25 μ</td>
<td>124 μ</td>
</tr>
<tr>
<td>Tank</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Number</td>
<td>2±2</td>
<td>1</td>
</tr>
<tr>
<td>Capacity*</td>
<td>40~60X</td>
<td>30X</td>
</tr>
<tr>
<td>System components</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Centrifugal cleaner</td>
<td>Always in operation while</td>
<td>Put to work as deemed</td>
</tr>
<tr>
<td>Material for tank and valve</td>
<td>the mill is running</td>
<td>necessary on inspecting the</td>
</tr>
<tr>
<td></td>
<td>Stainless steel</td>
<td>oil</td>
</tr>
<tr>
<td>Controlling of</td>
<td></td>
<td></td>
</tr>
<tr>
<td>lubricant oil</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Contamination</td>
<td>Weight method 104~107 by</td>
<td>Change of oil if failed to</td>
</tr>
<tr>
<td></td>
<td>NAS</td>
<td>meet either index</td>
</tr>
<tr>
<td></td>
<td>Count method 7~9 by NAS</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Once a month</td>
<td></td>
</tr>
<tr>
<td>Water content</td>
<td>Control index</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0.1%</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Checking</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Once a month</td>
<td></td>
</tr>
<tr>
<td>General checking</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Once a month</td>
<td></td>
</tr>
</tbody>
</table>

* Maximum size of the throughput
** Alternatively put to service
*** Multiples of the pump delivery (/min)
**** Renewal if failed for either one

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6) Sangyo Kikai Kogyo 30 Nen Shi.
Table 9. Comparisons of various direct patenting methods.

<table>
<thead>
<tr>
<th>Method</th>
<th>Features</th>
<th>Main coolant</th>
<th>Quality of product</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stelmore</td>
<td>The wire, shaken out at the laying head eccentrically, is moved by conveyor and cooled uniformly by air blast.</td>
<td>Air blast</td>
<td>• Mechanical properties equivalent to or even better than the air patented stocks.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Good drawability</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Little scale loss</td>
</tr>
<tr>
<td>Vertically descending</td>
<td>The wire, shaken out into spiral, is held between a pair of vertically descending conveyors with a given pitch and air-cooled.</td>
<td>Air blast</td>
<td>• Mechanical properties equivalent to the air patented stocks.</td>
</tr>
<tr>
<td>conveyor</td>
<td></td>
<td></td>
<td>• Good drawability</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Little scale loss</td>
</tr>
<tr>
<td>Fluidized bed cooler</td>
<td>The wire is spirally and continually dropped into a fluidized bed and cooled uniformly.</td>
<td>Sand</td>
<td>• Mechanical properties equivalent to or even better than the air patented stocks.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Good drawability</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Very little scale loss</td>
</tr>
<tr>
<td>Boiling water</td>
<td>The wire is led into a hot water bath as it is unwound from the coiler.</td>
<td>Hot water</td>
<td>• Suitable for large lot.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Good drawability</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Very little scale loss</td>
</tr>
</tbody>
</table>

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Fig. 40. Comparison of drawability.

Fig. 41. Comparison of tensile strength.
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