1. Introduction

In the next decade, concerns about global climate change and energy security will create the platform for the introduction of hydrogen to several niche markets, and ultimately, hydrogen and electricity will come from sustainable renewable energy sources, while fossil fuels will be the transitional resources during this period. The improvement of fuel cell technology will provide a basis for the establishment of the hydrogen option in both transportation and electricity supply markets. To ensure the safety of the hydrogen energy system, new hydrogen gas sensors, for robust, reliable, and cost-effective devices for widespread use must be developed within a developing hydrogen infrastructure. In addition, they should be small, affordable and easy to implant on integrated circuits, such as film type, or integrated micro-machined hydrogen gas sensors. However, the present hydrogen sensors commercialized or under development are still very expensive and most of them are for very high hydrogen concentrations and useless above 1% levels.1

Recently, we have demonstrated a new thick-film-type thermoelectric (TE) gas sensor operating at room temperature for detecting 3% hydrogen gas.2) Since TE material can convert thermal energy to electrical work without any special structures, it is used for not only TE power generation, the classical application, but also sensor applications in the measurement of thermal signals or detection of infrared radiation signals.3) The operating principle of our novel thick-film TE hydrogen sensor is similar to that in previous reports in which heat energy from a catalytic reaction is converted by the thermoelectric4) or pyroelectric effect.5) First, the catalytic reaction produces heat, and then, analogous to thermocouples, a voltage difference is induced by the temperature gradient, \( \Delta V = \alpha \Delta T \), where \( \alpha \) is the thermopower (or Seebeck coefficient). The TE figure of merit is defined by \( Z = (\alpha^2 \sigma) / \kappa \), where \( \sigma \) is the electrical conductivity and \( \kappa \) is the thermal conductivity. A high \( Z \) material is required for increasing the cross-sensitivity, and the temperature difference separately. The calculated thermopower of the thick oxide film is also discussed.

Key-words: Hydrogen, Gas sensor, Thermoelectric, Thick-film oxides, Pt catalyst

2. Experimental procedures

2.1 Material choice and device structure

The sensor is fabricated by screen printing the thermoelectric Li, Na-doped nickel oxide, TEO, on an alumina substrate. The TEO layers were printed with a viscous paste, which was a mixture of the NiO powders doped with Li, Na ions and organic vehicle. The nominal composition of the NiO powder was 5.0 mol% Na, and 2.0 mass% Li2O.7) The organic vehicle was a blend of terpineol and ethyl cellulose. The size of the apertures in the net was 200 mesh, and the snap-off value (the distance between the net and the substrate) was 1 mm. By changing the number of printing times, the thickness of the TEO film was controlled. After every printing, a 5min drying at 200ºC was carried out and then the sample was finally fired at 1000ºC for 2h.

To achieve high hydrogen selectivity, the Pt layer was used as a catalyst for the designed hydrogen element. Pt thin film was deposited at room temperature by rf sputtering on the half of the TEO surface, using a metal mask. The distance between the substrate and the target was 70 mm, with the flow of Ar gas at 20 cc/min, and the working pressure at 2.3 × 10⁻² Pa. The structure of the sensor device is shown in Fig. 1. The Pt-catalyst layer effectively converts \( \text{H}_2 \) to \( \text{H}_2\text{O} \) with the O atoms adsorbed on the Pt surface, and gives out heat energy, resulting in the temperature difference between the hot and cold regions of the TEO layer. The Pt sensor reliability, are reported.

We report herein our study on this thick-film thermoelectric hydrogen gas sensor based on the Li, Na-doped NiO and a Pt catalyst. NiO is a good TE oxide (TEO). It is easy to control its electrical conductivity by alkali doping and the conductivity or thermopower is little affected by Pt. Pt is selected as the catalyst for improving room temperature hydrogen selectivity, while TE materials may play an important role in activating the catalytic reaction. The performance test reported here will provide data on the response characteristics, speed and sensitivity, all of which will be advantageous for defining appropriate applications and guiding the engineering design of sensor packaging and electronics. Also, the results related to cross-sensitivity, and the dependence on the device-operating temperature, which improves sensor reliability, are reported.
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point pads of 1 mm diameter were prepared on top of the Pt catalyst and TEO using Ag paste, and Au wires of 0.1 mm diameter were connected to the pads to read the voltage signal.

The most important parameter of the sensor device is the dimensions of the catalyst layer. The substrate is 22 length × 11 width × 1 thickness mm³, the TEO layer is 18 × 5 mm², and the Pt catalyst covers half of the TEO layer, i.e., 9 × 5 mm². This set of dimensions is optimized by pre-experiments and used throughout this study. The thicknesses of TEO and the Pt layer are important parameters in this study and will be discussed in detail here.

2.2 Characterization

For the response test, gas mixtures containing ppm or % level hydrogen can be conveniently obtained by using a gas syringe. Here, a chamber with a rubber septum is used into which dry air can be introduced. A pure sample gas is drawn into a calibrated gas syringe, with a needle pushing through the septum. The desired concentration could be obtained by injecting a known volume of pure gas into a known volume of dry air. Flows of the mixture gas and dry air are changed by electrically controlled valves. A four-way valve directs two flows, mixture gas and clean air, alternately into a measuring chamber so that the response speed of the sensor can be obtained in a second by switching one gas stream to the others quickly.

To evaluate and investigate the properties of TEO and catalyst for this thermoelectric gas sensor device, the voltage signal $V_s$ and the built-up temperature difference $\Delta T$ on the surface of the device must be measured separately.

Non-contact in situ temperature monitoring enabled us to measure $V_s$ and $\Delta T$ separately through the window of the measurement chamber using an infrared image camera (Nikon, LAIRD-270A). Surface temperatures near the voltage lead pad were measured to evaluate $\Delta T$.

The entire measurement system including the camera system, the gas-flow manipulation system and the multi-channel data acquisition system is simultaneously controlled by a personal computer. For the material characterization, XRD (Rigaku, RINT2100) and FE-SEM (JEOL, JSM 6335F) were used.

3. Results and discussion

3.1 Thick-film thermoelectric oxide

The thickness of the NiO TEO film increased with increasing number of printing times. When the printing time was 1, 2, 4, or 6 times, the thickness of the film was 13.3, 25.6, 35.5, or 56 μm, respectively. The thickness of the film was the average value obtained by SEM observation of the cross section, as shown in Fig. 2. A thickness of about 10 μm can be achieved by single printing under the conditions described in this study.

We fixed the thickness at 60 μm (6 printing times) for all thick-film samples for the gas sensor device, which gave the lowest resistance and the reduced noise. When the thickness was increased to 80 and 100 μm, the final film surface became very rough and had many cracks, which increased the resistance of the device and suppressed the following process. It was much easier to control the film thickness by adjusting the number of printing times than by other parameters, for example, viscosity of the paste, mesh size of the net, and the snap-off value, etc.

The thickness of the Pt catalyst could not be observed directly on the surface of the TEO film since the roughness of the thick film is larger than the thickness of the Pt thin film. However, the Pt film on the polished Si wafer deposited in the same batch was used to predict the thickness, which corresponded to 20 nm. The thickness of the Pt film on the polished Si wafer was evaluated from the deposition time-thickness relation (a preliminary experiment in which a series of films with thicknesses of 100, 300 and 700 nm were made and their cross sections directly observed by FE-SEM). Atomic force microscopy of Pt film on the Si wafer revealed that small particles with a diameter of around 20 nm agglomerate, covering the whole surface. The Pt film catalyst was much thicker than reported in which films of several nanometers thickness were suggested.

As shown in Fig. 2, the grains of the TEO thick film con-
tacted each other by neck. Their size was about 1 \( \mu m \) or less and was almost same to the size of the starting powder. When the sintering temperature was increased up to 1250°C for 2 h, the grain size increased to 2-3 \( \mu m \), but the resistance was as high as 10 M\( \Omega \). The sintering conditions of 1000°C for 2 h were the optimum considering the thermoelectric power and the resistance of the sensor device. At a lower sintering temperature of 900°C, the resistance became higher than that at 1000°C. It is suggested that active volume diffusion at the sintering temperature of 1000°C induces the grain contact each other, and that much Li is lost at much higher temperatures.

The resistance read from the voltage leads for thick films sintered at the conditions of 1000°C for 2 h was 0.5-1.0 M\( \Omega \) at room temperature. Assuming that the contact resistance is zero, the resistivity of the thick film is 15-30 \( \Omega \) cm, which is almost the same as that of bulk sample with the same nominal composition, i.e., about 1-10 \( \Omega \) cm, from a previous report. The lattice constant of NiO changes with the Li content, as revealed by XRD analysis. From the XRD patterns of the thick-film NiO/alumina, the lattice constant calculated from the (111) plane for the cubic lattice was 0.41656 nm, corresponding to 0.6 mol\% Li doping. From this resistivity analysis, the expected thermoelectric power, Seebeck coefficient, is about 0.4 mV/K.

### 3.2 Response of gas sensor device

The measured voltage signal, \( V_s \), and the built-up temperature difference, \( \Delta T \), for the thermoelectric hydrogen sensor, Pt/NiO/alumina, when exposed to 1% \( H_2/air \) mixture gas at 25°C, were 0.079 mV and 0.15, respectively, as shown in Fig. 3(a). Response time \( T_{90} \) and recovery time \( T_{90D} \) are defined as follows: \( T_{90} \) is the time to reach 90% of \( V_s \), \( T_{90D} \) is the time to decrease to 10% of \( V_s \). \( T_{90} \) and \( T_{90D} \) were 70 s and 50 s, respectively. This response is very fast considering room temperature operation. The response of other gas sensors such as a semiconductor type at room temperature, is much slower; \( T_{90D} \) in particular is usually about 5-10 min. Both \( T_{90} \) and \( T_{90D} \) became a slightly faster at 40-50 s even at temperatures exceeding 85°C.

Figure 3(b) shows the temperature change at the two voltage leads. \( \Delta T \) in Fig. 3(a) was plotted from these raw data. The temperature at the two voltage leads, A, the Pt-catalyst side, and B, the bare-TEO-surface side, increased monotonically when hydrogen gas flows, and decreased in the same manner; however; \( \Delta T \) in Fig. 3(a) showed very clear signals. After \( T_{90} \), the voltage signal reached \( V_s \) level, and after \( T_{90D} \), the voltage signal reached zero level again. These clear responses were also obtained under other conditions, such as different hydrogen concentrations and different operating temperatures, with high reliability.

The reason for the clear \( V_s \) signal is that the temperature difference was used as the sensing mechanism; in contrast, other sensors that use the resistance change with temperature as the sensing mechanism need very careful control of the operating temperature. For hot-coil (catalytic-combustion) sensors that use the resistance change for sensing, the signal will be extremely small (for example, the temperature coefficient of Pt resistivity is only \(-4 \times 10^{-3}/°C\)) and noisy due to temperature fluctuations. The signal-to-noise ratio for the response curve in the Fig. 3(a) is 16. This is the unique feature of the novel thermoelectric gas sensor device in this study, which gives a stable signal level and a high signal-to-noise ratio. This operating mechanism is also advantageous for the temperature stability of the signal as will be discussed later.

However, the response characteristics at room temperature are not reproducible. They depend mostly on the surface state of the Pt catalyst and its history. This problem was solved by increasing the operating temperature up to 100°C, where the surface of the catalyst can refresh by itself. High-temperature operation also has other advantages as discussed in the next section.

### 3.3 Linearity for gas concentration

Figure 4(a) shows the operating temperature dependence of the voltage signal of the thermoelectric hydrogen sensor, Pt/NiO/alumina, for 1, 3 and 10% \( H_2/air \). Near room temperature, \( V_s \) is very low and there is no clear relationship between voltage and gas concentration. However, as the temperature increased, the voltage signal increased due to the enhanced catalytic activity, and saturated at around 85°C. In the temperature range of 85-150°C, \( V_s \) was nearly constant and its temperature dependency was extremely small. It is proven that Pt catalytic activity reaches its maximum at 85°C. For instance, for 1% \( H_2/air \), comparing the \( V_s \) at room temperature, the \( V_s \) became 10 times higher. The resistance of the sensor device, \( R \), which is the origin of the noise, also reduced from 1 M\( \Omega \) to 100 k\( \Omega \) with increasing temperature. The \( R \) values for 25, 85, 100 and 145°C were 1061, 207, 143 and 58.8 k\( \Omega \), respectively.

In this flat region of 85-150°C, the linearity of \( V_s \) vs. gas concentration is also very good; thus, the present sensor shows much promise for device design and application, considering that other gas sensor devices generally show an exponential behavior for the concentration vs. signal plot. Since the temperature dependence of the thermoelectric power of the TEO in this temperature region is very small, the signal difference can be attributed to the heat generated by the oxidation reaction. Therefore, these temperature dependences were mostly due to the catalytic activity of the exothermic reaction, the oxidation of the gas. For practical applications, the temperature of the gas sensor device must be under such control, as PID control, and therefore most sensors have an auxiliary circuit inside the chip or the con-

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**Fig. 3.** Response of thermoelectric gas sensor, Pt/NiO/alumina, to 1% \( H_2/air \) at a temperature of 25°C, a) voltage signal, \( V_s \), and temperature difference, \( \Delta T \), and b) temperature changes near the two voltage electrodes, A and B.
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control board. However, this TE gas sensor has a stable and constant $V_s$ for the temperature region of 85–150°C. Thus, a heater line designed with a pre-set heater power of around 115°C will be sufficient for applications, allowing a temperature change of +35 to −30 depending on the operation environment.

3.4 Detection limit for hydrogen gas in air

The lower explosion limit of hydrogen is 4% in air. Therefore, as a hydrogen leakage detector or an alarm for protection against explosion, an alarm level is usually set for gas concentrations between 0.1% and 4% from a practical point of view. For the thermoelectric hydrogen sensor, the percent-level detection of hydrogen in the range of 1–10% was very appropriate and showed good linearity, as shown in Fig. 4(b). The lower detection level is also very important and will be directly related to the size for the thermoelectric gas sensor. For sensors with a catalyst size of 0.9–0.5 ($=0.45$)cm² used in this study, the lower detection limit was below 250 ppm.

Figure 5 shows the response curves of the sensor for 250 and 1000 ppm hydrogen at 100°C. The linearity of $V_s$ for the given gas concentrations is excellent, e.g., 1% hydrogen gas corresponds to 1 mV, and 1000 and 250 ppm correspond to 0.10 and 0.24 mV, respectively. The results suggest that the thermoelectric sensor introduced in this report is suitable for actual applications even in its present form.

4. Summary

A new hydrogen sensor based on the thermoelectric oxide of Li- and Na-doped NiO has been fabricated using the screen printing method. The thermoelectric hydrogen sensor, Pt/NiO/alumina, showed voltage signal and built-up temperature difference for 1% H₂/air mixture gas. At 25°C, the voltage signal and temperature difference were 0.079 mV and 0.15°C, respectively, and the signal-to-noise ratio was 16. The increase in operating temperature up to the range of 85–150°C made the catalytic activity more stable, and the response characteristics were also improved. A very clear voltage signal of 1 mV for 1% hydrogen gas was observed, and the sensor showed extremely small temperature dependence. The sensor possesses a good linear relationship between the voltage signal and the gas concentration at this operating temperature range.

The lower detection limit of the sensor was found to be below 250 ppm, and the sensor provides an output level of 0.1 to 10 mV, which corresponds to practical gas concentrations of hundred ppm order to several percent with a high signal-to-noise ratio. From these results, we conclude that this sensor is the most promising candidate for fast and affordable hydrogen leakage detectors for fuel cell driving systems.

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References