1. Introduction

It is known that a crack occurs because of a fatigue accumulation in a metallic material. Then, the metallic component that exists in our surroundings breaks because of the fatigue accumulation. The fatigue accumulation is generated by external cyclic stress and thermal cyclic stress. To prevent any serious accidents caused by the fatigue accumulation, a conventional non-destructive testing gave priority to the discovery of the minute crack that occurred in the metallic components. However, the period from the appearance of the minute cracks of metallic parts to destruction is generally short. If we can know of the fatigue accumulation before the crack initiation, the adequate time can be obtained to prevent accidents. Therefore, research to evaluate the fatigue accumulation before the crack occurs in the metallic component has been active in recent years. We are also researching an evaluation method for a fatigue accumulated in the iron-based structural materials using the electromagnetic phenomena.

Many fatigue evaluation methods are being researched by different researchers. It is one of the important topics in this field. It is well known that magnetism and the micro-structure of the material are closely related. Thus, the attempt to evaluate the material deterioration from the change in the Barkhausen noise has been performed [1, 2, 3]. Moreover, the magnetic property of the magnetic materials was evaluated by the minor loop of B-H curve [4]. In such a research situation, our group has researched which deterioration in stainless steels and low carbon steel is evaluated by the residual magnetization method [5] and the eddy current testing (ECT) method. In our previous research results, the ECT method attained good results in the detection of fatigue in the metallic components caused by the plane bending fatigue and partially pulsating stress [6, 7].

However, these fatigue evaluation methods using the ECT method still contain some problems. When the specimen is a magnetic material, its permeability is large and its resistivity is small. Then, the eddy current by excitation concentrates on the surface of the specimen due to the skin effect. The inside fatigue of the specimen is not appreciable. The ECT method that uses the high excitation frequency is not appropriate to evaluate the deep inside fatigue of a specimen. In addition, there is a problem in that the surface condition of the specimen strongly influences the result of the fatigue evaluation. It is necessary to solve these two problems. To solve the skin effect problem of the ECT method when the specimen was a magnetic material such as SS400, we devised the following two methods. The first device point is to use the low excitation frequency. In this paper, 10 kHz were used as an excitation frequency. The other device points were to overlap the dc magnetic field to the alternating field with an Nd magnet. When a strong dc magnetic field was applied to the specimen, permeability was able to be reduced.

In order to evaluate the fatigue accumulation in an iron-based structural metallic material, we apply a non-destructive fatigue evaluation method for SS400 using the inductance method composed of a pancake-type coil that uses a low excitation frequency of about 10 kHz and the dc magnetic field generated by the Nd magnet. This paper describes the new non-destructive fatigue evaluation method for SS400.

2. Principle of the Inductance Method

2.1 The Principle of the Inductance Method

Fig. 1 shows the principle of the inductance method that used a pancake-type coil. When a pancake-type coil
is excited by an alternate current, an eddy current \( J_e \) (A/m²) is induced in a specimen as shown in Fig. 1. Then, the eddy current can be written as Eq. (1), where \( \mu \) (H/m) and \( \rho \) (Ωm) are permeability and resistivity of a specimen, respectively. Eq. (1) contains \( \mu \) and \( \rho \) of a specimen. Therefore, an eddy current in a specimen changes when electromagnetic properties such as \( \mu \) and \( \rho \) of a specimen changes by fatigue. An inductance \( L \) (H) of a pancake-type coil is influenced by the change of \( \mu \) and \( \rho \). If \( L \) can be measured, we can know the amount of fatigue damage of a specimen.

\[
\nabla^2 J_e = \frac{\mu}{\rho} \frac{\partial J_e}{\partial t} \quad (1)
\]

2.2 The Pancake-Type Coil

Fig. 2 (a) shows dimensions of the pancake-type coil. Fig. 2 (b) shows the photograph of the pancake-type coil that is a same shape pancake-type coil used in the experiment. The number of turns in the pancake-type coil and the diameter of copper wire were 324 turns and 0.04 mm, respectively. The inductance \( L \) and impedance phase angle \( \theta \) (degrees) of the pancake-type coil were 320.2 \( \mu \)H and 22.9 degrees when it was in the air and the excitation frequency \( f_{ex} \) was 10 kHz.

3. Specimen and Experiment

3.1 The Specimen

The specimen was made of hot rolled general structural steel (SS400). Fig. 3 shows the dimensions of a specimen and arrangement of the measurement area. Arrangements of Nd magnets are shown. The thickness of the specimen was about 1.2 mm. To exclude residual stress caused by mechanical processing, specimens used in this experiment were cut in the shape shown in Fig. 3 by the electrical discharge machining method. Tensile strength of this specimen was about 400 MPa. The specimen used for this experiment did not perform pretreating such as annealing.

The dc magnetic field was generated with an Nd magnet. Two Nd magnets were arranged to the series as shown in Fig. 3. The magnetic path was composed of two yokes made of SS400 and a specimen as shown in Fig. 3. The distance between the specimen and the upper side of the yoke was about 0.1 mm. When the specimen was excluded, the magnetic flux density at the upper surface of the yoke was 220 mT.

Fig. 4 shows the photograph of the specimen with a surface scratch, when \( N \) was \( 5 \times 10^4 \). This scratch was caused in the specimen, and it is thought that depth was very slight.

3.2 The Measurement System

Fig. 5 shows the block diagram of a measurement system for the inductance method. The pancake-type coil constants such as \( L \) and \( \theta \) were measured by the LCR meter (ZM2353, NF Corporation). Measured values of \( L \) and \( \theta \) were a mean value of the measurement result of two times. The 4-terminal method was used to obtain accurate \( L \) and \( \theta \). These measuring devices were controlled by the control computer. Then, the values of \( L \) and \( \theta \) of the pancake-type coil were collected by the automatic operation.

3.3 The Experimental Method

To make a clear relationship among the amount of fatigue damage, \( L \) and \( \theta \), experiments were carefully carried out in the procedure shown in Fig. 6. First, \( L \) and \( \theta \) were measured by using the LCR meter within the

Fig. 3. The dimension of a specimen (t = 1.2 mm) and arrangement of the pancake-type coil.

Fig. 4. Photograph of the specimen with a surface scratch (N = \( 5 \times 10^4 \)).
measurement area of 40 mm x 40 mm every 1 mm step. In our experiments, the excitation frequency and the excitation voltage were 10 kHz and 1 Vrms respectively. The lift-off, which is the distance between the specimen and the lower side of the pancake-type coil, was about 0.05 mm. Next, the partially pulsating stress was applied by the tensile and compression tester (V-0674, SAGINOMIYA SEISAKUSHO) which operated at 20 Hz. The maximum tensile force was about ±49 kN, and the maximum displacement amplitude was 30 mm. This procedure was repeated until the specimen was destroyed. Fig. 7 shows the photograph of a specimen set in the tensile and compression tester.

This experiment was a fatigue test that impressed the partially pulsating stress to the specimen. The following experiments were executed when the stress ratio ($R$) was 0.1. In this experiment, a stress waveform was a sinusoidal wave. The experiments were performed at room temperature. The running average processing was applied to the values of $L$ and $\theta$ shown in this paper.

3.4 S-N Curve of the Specimen

In order to know the fatigue limit of our specimen, we measured the relationship between the partially pulsating stress ($\sigma_a$ (MPa)) and the number of stress cycles ($N$) (S-N curve). This relationship is shown in Fig. 8. From Fig. 8, the fatigue limit of SS400 used in our experiments was estimated to be 110 MPa. The value of $\sigma_a$ of the following experiments was decided using this S-N curve. We used 100 MPa, 110 MPa, 115 MPa, 120 MPa, and 125 MPa as a value of $\sigma_a$. When stress is the plane bending stress, fatigue of metal such as austenitic stainless steels progresses even if applied stress is below the fatigue limit [8, 9]. Therefore, 100 MPa was used as one of $\sigma_a$.

3.5 $L$ and $\theta$ of the Pancake-Type Coil

Table 1 shows the value of $L$ and $\theta$ under some conditions. These values were measured using a LCR meter (ZM2353) when $f_{ex}$ was 10 kHz. $L_s$ is $L$ of the pancake-type coil on the center part of the specimen when the dc magnetic field was not applied, and $L_m$ is $L$ of it on the center part of the specimen when the dc magnetic field was applied. When the pancake-type coil was in air, $L_s$ is $L$ of it. $L_m$ was influenced by $\mu$ and $\rho$ of the specimen and was larger than $L_s$. However, because the magnetic flux density in the specimen is saturated by the dc magnetic field, $\mu$ in this case has become small. Therefore, $L_m$ has become smaller than $L_s$. When fatigue was applied to the specimen, $L$ and $\theta$ of the pancake-type coil are influenced also by $\rho$ of the specimen changed by fatigue.

3.6 Skin Depth ($\delta$)

Table 2 shows the skin depth ($\delta$) under some conditions. The skin depth was calculated using the resistivity ($\rho = 9.8 \times 10^{-8} \Omega \cdot m$) of the specimen and the excitation frequency ($f_{ex} = 10$ kHz). Here, relative permeability ($\mu_r$) of SS400 was assumed to be 200 when there was not a dc magnetic field. In this case, only fatigue near the surface of the specimen is evaluated. Moreover, the fatigue detection signal is strongly influenced by a scratch on the surface of the specimen. On the other hand, $\mu_r$ was assumed to be ten in consideration of the influence of the magnetic saturation of the specimen when there was a dc magnetic field. If the dc magnetic field is applied, the skin depth grows very much as shown in Table 2. Therefore, if the dc magnetic field is applied, information on fatigue of the inside of the specimen can be obtained without receiving the influence of the surface condition of the specimen.

4. Experimental Results and Discussions

4.1 The Distribution of $L$ without or with Nd Magnet

Fig. 9 (a) shows the distribution of $L$ at each measurement position when $\sigma_a$ and the number of stress cycles ($N$) were 115 MPa and zero, respectively. Fig. 9 (b) shows the same relation as Fig. 8 (a), when $N$ was $2 \times 10^6$. In these cases, Nd magnets were not installed.

Fig. 8. The relationship between $\sigma_a$ and $N$. 

Fig. 7. Photograph of a specimen set in the tensile and compression tester.
The average value \( (L_{\text{ave}}) \) of \( L \) within 3 mm x 3 mm of the central portion of the measurement range in Fig. 9 (a) was 463.7 \( \mu \)H. In Fig. 9 (b), \( L_{\text{ave}} \) was 464.8 \( \mu \)H. However, this difference is not understood from both figures. In Fig. 10, the \( L \) axis of this figure had expanded about 50 times compared with the \( L \) axis of Fig. 9. Moreover, \( dL \) was calculated by the following Eq. (2).

\[
dL = L - L_{\text{ave}}.
\] (2)

In Fig. 10, the distribution of \( dL \) is not smooth due to non-homogeneity of the electromagnetic properties of the specimen. If Figs. 10 (a) and 10 (b) are compared, it is understood that \( dL \) has changed by fatigue induced by partially pulsating stress. On the other hand, Fig. 11 shows the same relationship as Fig. 10. In Fig. 11, Nd magnets were installed. In Figs. 11 (a) and 11 (b), \( L_{\text{ave}} \) were 410.5 \( \mu \)H and 410.8 \( \mu \)H, respectively. When both figures are compared, the change in the distribution of \( dL \) by fatigue cannot be clearly confirmed as in Fig. 10. From Figs. 10 and 11, it can be said that the change of the specimen's electromagnetic properties (\( \rho \) and \( \mu \)) which was caused by fatigue due to partially pulsating stress was small.

4.3 Influence of Surface Scratch on a Specimen

Fig. 13 shows the distribution of \( dL \) without Nd magnets when \( f_{\text{ex}} \) was 100 kHz. In this case, the skin depth was 35.2 \( \mu \)m. The scratch strongly influences the distribution of \( dL \) in the inside of the black oval shown in Fig. 13. However, when \( f_{\text{ex}} \) was 10 kHz, the influence of the scratch became small as shown in Fig. 14. In addition, when the dc magnetic field was applied, the influence of the scratch became even smaller as shown in Fig. 15. This phenomenon can be described by the following two reasons. The first reason is a decrease in the excitation frequency. The second reason is a decrease in permeability of the specimen by the magnetic saturation. It is well known that both reasons bring an increase in the skin depth.

4.2 The Distribution of \( \theta \)

Fig. 12 shows the distribution of \( \theta \) at each measurement position. Nd magnets were not installed in Fig. 12 (a), and they were installed in Fig. 12 (b). When both figures are compared, the change in the distribution of \( \theta \) by fatigue cannot be clearly confirmed.

Table 1. Values of \( L \) and \( \theta \) under some conditions

<table>
<thead>
<tr>
<th>( f_{\text{ex}} = 10, \text{kHz} )</th>
<th>( L ) [( \mu )H]</th>
<th>( \theta ) [degrees]</th>
</tr>
</thead>
<tbody>
<tr>
<td>On specimen</td>
<td>Without Magnet</td>
<td>( L_s )</td>
</tr>
<tr>
<td></td>
<td>With Magnet</td>
<td>( L_{m} )</td>
</tr>
<tr>
<td>In air</td>
<td></td>
<td>( L_a )</td>
</tr>
</tbody>
</table>

Table 2. Skin depth (\( \delta \)) under some conditions

<table>
<thead>
<tr>
<th>( f_{\text{ex}} = 10, \text{kHz} )</th>
<th>( \mu )</th>
<th>Skin depth ( \delta ) [( \mu )m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Without magnet</td>
<td>200</td>
<td>111</td>
</tr>
<tr>
<td>With magnet</td>
<td>10</td>
<td>498</td>
</tr>
</tbody>
</table>

4.4 Relationship among \( L_{\text{ave}}, \theta_{\text{ave}}, N, \) and \( \sigma_{a} \)

In this paper, \( L_{\text{ave}} \) was used as a parameter that evaluated fatigue in SS400.

Fig. 16 shows the relationship among \( L_{\text{ave}}, N, \) and \( \sigma_{a} \) with Nd magnets when \( f_{\text{ex}} \) was 10 kHz. Fig. 17 shows the same relation as Fig. 16 when the dc magnetic field was not applied. \( L_{\text{ave}} \) has been somewhat changed by...
fatigue in both figures. Therefore, there is a possibility that $L_{\text{ave}}$ can be used as a parameter that evaluates fatigue of SS400. Fig. 18 shows the relationship among $\theta_{\text{ave}}$, $N$, and $\sigma_{\text{a}}$ with Nd magnets when $f_{\text{ex}}$ was 10 kHz. $\theta_{\text{ave}}$ was calculated as $L_{\text{ave}}$ in a similar method. The good correlation between $\theta_{\text{ave}}$, $\sigma_{\text{a}}$, and $N$ doesn't exist in Fig. 18. Therefore, it cannot be said that $\theta_{\text{ave}}$ is a good parameter for the fatigue evaluation of SS400.

Figs. 19 and 20 were rewritten as having the same relation as Figs. 16 and 17 based on the value of $L_{\text{ave}}$ when $N$ was $1 \times 10^4$. In Fig. 19, $dL_{\text{ave}}$ increases almost monotonously according to an increase in $N$, except when $\sigma_{\text{a}}$ is 120 MPa. When the dc magnetic field was applied, permeability became very small. Then, the increase in the resistivity contributed more to $dL_{\text{ave}}$ than the decrease in permeability. This is the reason why $dL_{\text{ave}}$ increases almost monotonously. In Fig. 20, $dL_{\text{ave}}$ decreases with an increase in $N$ once, and tends to increase afterwards. In this case, the permeability of the specimen was large. Therefore, a decrease in permeability by fatigue greatly contributed to changing $dL_{\text{ave}}$ at the initial stage of fatigue. When $N$ grows, a decrease in permeability by fatigue was saturated. An increase in the resistivity contributes to the change of $dL_{\text{ave}}$ afterwards.

From these figures, $dL_{\text{ave}}$ under the dc magnetic field is proportional to $N$. Therefore, under the dc magnetic field it can be said that there is a possibility to be able to use $dL_{\text{ave}}$ as the parameter of the fatigue evaluation of SS400.
5. Conclusion

In this paper, we applied the new inductance method to the fatigue evaluation of SS400. The new inductance method used for this experiment applied the low excitation frequency and the dc magnetic field. As a result, the correlation among the inductance of the pancake-type coil and the amount of fatigue damage of SS400 was obtained. This method was able to reduce the influence of the surface condition of the specimen. $dL_{ave}$ under the dc magnetic field can be used as the parameter of the fatigue evaluation in the magnetic materials, the improvement of the inductance method is needed in the future.

Acknowledgment

This work was supported in part by the Japan Society for the Promotion of Science under Grant No. 23560518.

References


